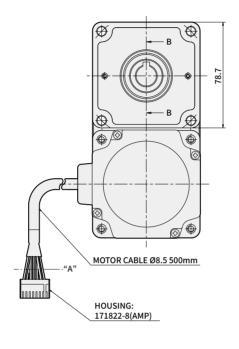
BRUSHLESS DC MOTOR UNIT - L Series

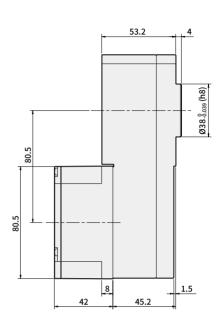
DIMENSIONS

K8LH50N2 + K8H□BTH

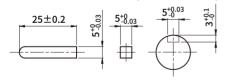
(Weight: 2.3Kg)





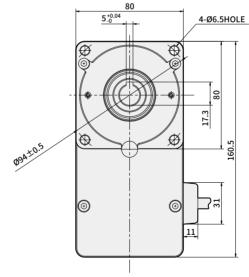


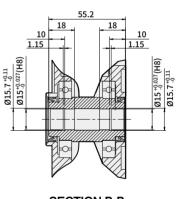
* KEY · KEY GROOVE (ACCESSORY)



* CONNECTOR HOUSING (VIEW A)







SECTION B-B

MOTOR PRODUCT NAME		GEARHEAD PRODUCT NAME	DECELERATION RATIO	FIXING BOLT	
	K8LH50N2	К8Н□ВТН	5~200	M6 P1.0×70	

- * In □ of name, it represents a deceleration ratio.
- * Mounting bolt sets are included in flat type gearbox. M6×70L (flat washer, spring washer, hexagonal nut 4pcs each)

* PIN MAP

PIN No.	COLOR	SIGNAL		
1	GRAY	W		
2	PURPLE	V		
3	BLUE	U		
4	YELLOW	Vcc		
5	GREEN	Ground		
6	ORANGE	Hw		
7	WHITE	Hv		
8	BROWN	Hu		



Specification

Product	GEAR TYPE	K6LH30N2	K8LH50N2	K9LH100N2			
name	D-CUT TYPE	K6LS30N2	K8LS50N2	K9LS100N2			
Rating outp	ut (continuous) W	30	50	100			
	Rating voltage V	DC24					
Power	Rating voltage allowance	±10%					
input	Rating input current A	2.1	3.1	6.0			
	Rating output current A	3.7	5.4	9.8			
Rating torqu	ue N·m(kgf·cm)	0.12	0.2	0.4			
Starting tor	que N·m(kgf·cm)	0.15	0.24	0.5			
Rating rotat	tion speed r/min	2500					
Speed contr	rol range r/min	100~3000					
Allowed iner	rtia load moment J×10 ⁻⁴ kg·m²	1.8	3.3	5.6			
Rotor inertia	a moment J×10 ⁻⁴ kg·m ²	0.086	0.234	0.611			
	Load	Less than or equal to ±1%: condition 0-rated torque, rated rotation speed, rated voltage, room temperature					
Speed change rate	Voltage	Less than or equal to ±1%: condition rating voltage ±10%, rating rotation speed, no load, room temperature					
	Temperature	Less than or equal to ±1% : condition surrounding temperature 0~+40℃, rating rotation speed, no load, rating voltage					

- $\star\,$ The usage duration for stabting torque is within 5 seconds at less than 2000 r/min
- * Each specification value is the characteristic of motor by itself

Common specifications

Product name	Specification
Rotation speed setting method	 Set up by external potentiometer Set up by external DC 0~5V
Acceleration time deceleration time	0.5~10 seconds: set at 2000 r/min when there is no load (it may change depending on the size of the load) Accleration time and deceleration control equipment to control at the same time
Input signal	Internal full-up input method, external input voltage read as greater than 2v high(off) same at all input ports
Output signal	Open collector output, common for speed out/alarm out, if input voltage from out side is applied to connector #2 pin, then it comes out through the applied power. Everything else is internal 5V ouput UI(CTRL)
Protection function	If the following protection mode comes on, cotrol unit alarm signal is shown. Motor stops automatically. Overload protection mode: If torque that is greater than the rating is applied to the motor for more than 5 seconds Overvoltage protection: If voltage applied to the control unit goes over the upper bound of the rating allowance Open phase protection: If cable sensor line gets disconnected during motor operation Undervoltage protection: If voltage applied to the control unit is less than the lower bound of th rating voltage allowance Over speed protection: If motor rotation speed is faster than 2500 r/min
Motor insulation class	E TYPE(120°c)
Maximum extension distance	MOTOR - CONTROL UNIT 2m
Rated time	Continuous

^{*} Like weight carried being downwards, L SERIES cannot control motor speed through weight.

Motor gets stopped automatically through overvoltage protection of load is being carried downwards or it is heavier than allowed load inertia.



Normal specifications

Items		Motor	Control unit			
Insulation Resistance		After being operated continuously at room temperature and humidity, the value measured between coil and vase by DC 500V MEGA is greater than or equal to 100\omega	After being operated continuously at room temperature and humidity, the value measured between heatproof plate and power input is greater than or equal to 100 ΜΩ			
Dielectric Strength		After being operated continuously at room temperature and humidity, there shouldn't be any problem between coil and case even when AC 0.5kV is applied for 1 minute	No problem when 50Hz, AC 0.5kV is applied for one minute No problem when AC 0.5kV is applied for one minute			
	Used Ambient temperature	0℃~+50℃ (shc	ould not freeze)			
	Used Ambient Humidity	less than or equal to 85% (not from dews)				
Used	Vibration	Altitude less than 1000m				
environment	Ambient environment	Cannot be used under special corrosive gas, dust, radioactive				
	Vibration	Should not apply constant vibration or huge impact according to the JIS C 60068-2-6 sine wave vibration test method Frequency range: 10~55Hz, peak amplitude: 0.15mm, sweet direction: 3 direction(X,Y,Z), number of sweeps: 20 times				
	Ambient temperature	-25 ~ +70°C (should not freeze)				
Conservation environment	Ambient Humidity	less than or equal to 85% (not form dews)				
	Altitude	Altitude less	than 3000m			
Insulation class		UL, CSA STANDARD A TYPE(105୯), EN STANDARD E TYPE(120୯)				
Protection class		IP65	IP00			

- * Preservation environment is a short-term value, which includes transportation.
- * Do not measure insulation resistance and pressure resistance while motor and driver are connected

Allowed torque of combination type

Unit = upper part : N·m / lower part : kgf·cm

	Deceleration ratio		5	10	15	20	30	50	100	200
Items	Crood control rongo [n/min]		20~500	10~250	6.7~167	5~125	3.3~83	2~50	1~25	0.5~12.5
Speed control range [r/min]		600	300	200	150	100	60	30	15	
K6LH30N2 + K6H□B		100~2500r/min	0.54 5.4	1.1 11	1.6 16	2.2 22	3.1 31	5.2 52	6 60	6 60
KOLII	SUNZ T KONLID	3000r/min	0.27 2.7	0.54 5.4	0.81 8.1	1.1 11	1.5 15	2.6 26	5.2 52	6 60
V 01 П	100~2500r/mi		0.9 9	1.8 18	2.7 27	3.6 36	5.2 52	8.6 86	16 160	16 160
K8LH50N2 + K8H□B		3000r/min	0.45 4.5	0.9 9	1.4 14	1.8 18	2.6 26	4.3 43	8.6 86	16 160
VOLU1		100~2500r/min	1.8 18	3.6 36	5.4 54	7.2 72	10.3 103	17.2 172	30 300	30 300
K9LH100N2 + K9H□B		3000r/min	0.9 9	1.8 18	2.7 27	3.6 36	5.2 52	8.6 86	17.2 172	30 300
V61 U2	0N2 + K6H□BTH	100~2500r/min	0.48 4.8	1 10	1.5 15	2 20	3.1 31	5.1 51	10.2 102	17 170
KOLHS	UNZ + KOHLIBIH	3000r/min	0.24 2.4	0.51 5.1	0.77 7.7	1 10	1.5 15	2.6 26	5.1 51	10.2 102
VOI LIE	UNO ∓ NON⊟BIN	100~2500r/min	0.85 8.5	1.7 17	2.6 26	3.4 34	5.1 51	8.5 85	17 170	34 340
K8LH50N2 + K8H□BTH		3000r/min	0.43 4.3	0.85 8.5	1.3 13	1.7 17	2.6 26	4.3 43	8.5 85	17 170
K9LH100N2 + K9H□BTH		100~2500r/min	1.7 17	3.4 34	5.1 51	6.8 68	10.2 102	17 170	34 340	68 680
		3000r/min	0.85 8.5	1.7 17	2.6 26	3.4 34	5.1 51	8.5 85	17 170	34 340

- * Rotation direction shows the same _____ color as the motor. In other cases, it's the opposite.
- * Flat Gearbox viewed from front side is opposite rotation direction with motor. Flat Gearbox viewed from back side is same rotation direction with motor.



Allowed overhang load and allowed thrust

Product name			Allowed overhand load						
		Deceleration ratio	From the end of output part : 10mm		From the end of output part : 20mm		Allowed thrust load		
			N	kgf	N	kgf	N	kgf	
		5	100	10	150	15		4	
	K6LH30N2 + K6H□B	10~20	150	15	200	20	40		
		30~200	200	20	300	30			
		5	200	20	250	25			
	K8LH50N2 + K8H□B	10~20	300	30	350	35	100	10	
		30~200	450	45	550	55			
		5	300	30	400	40	150	15	
GEARED	K9LH100N2 + K9H□B	10~20	400	40	500	50			
MOTOR		30~200	500	50	650	65			
	K6LH30N2 + K6H□BTH	5~10	450	45	370	37	200	20	
		15~200	500	50	400	40			
	K8LH50N2	5~10	800	80	660	66	400	40	
	+ K8H□BTH	15~200	1200	120	1000	100	400	40	
		5~10	900	90	770	77			
	K9LH100N2 + K9H□BTH	15~20	1300	130	1110	111	500	50	
		30~200	1500	150	1280	128			
	K6LS30N2		70	7	100	10			
MOTOR	K8LS50N2		120	12	140	14	·Be careful not to weigh thr If it's inevitable, keep it und 50% of the motor weight		
	K9LS100N2		160	16	170	17			

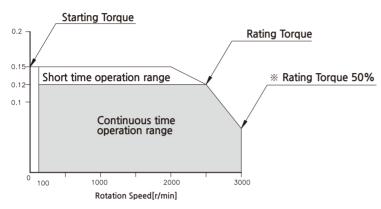
 $[\]star~$ In \square of name, it represents a deceleration ratio.

^{*} Permissible overhang load can be withdrawn by calulation.



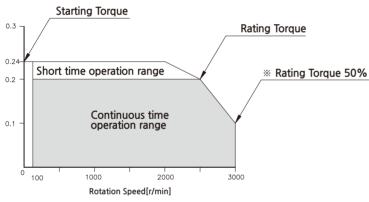
Rotation speed- torque characteristic

K6LS30N2 / K6LH30N2



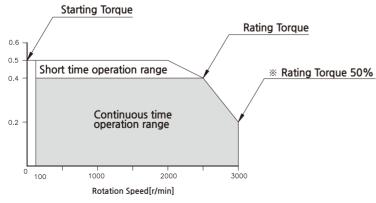
* DC24V is the value without cable extension.

K8LS50N2 / K8LH50N2



* DC24V is the value without cable extension.

K9LS100N2 / K9LH100N2



* DC24V is the value without cable extension.